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A feedback control system is formed of a unit-gain integral controller, a mechanical filter microsystem (plant), which is formed of two shuttle masses, and a connecting micro spring, with one mass being subjected to viscous damping and connected to another micro spring to the substrate.

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In this way, the controller dynamically counteracts changes to the car's speed. The central idea of these control systems is the feedback loop, the controller affects the system output, which in turn is measured and fed back to the controller. Classical control theory

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Notably, the feedback control transfer function of an integrated classical dynamic system and a quantum state is proposed. This paper addresses the application of quantum entanglement and cryptography for automation and control of dynamic systems. A dynamic system is a system where the rates of changes of its state variables are not negligible.

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If either the output or some part of the output is returned to the input side and utilized as part of the system input, then it is known as feedback. Feedback plays an important role in order to improve the performance of the control systems. In this chapter, let us discuss the types of feedback & effects of feedback.

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Electronic feedback loops are used to control the output of electronic devices, such as amplifiers. A feedback loop is created when all or some portion of the output is fed back to the input. A device is said to be operating open loop if no output feedback is being employed and closed loop if feedback is being used.

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