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continuous and discrete signals are defined as  $E_{\infty} = Z_{\infty} \rightarrow \infty |x(t)|^2 dx$  and  $E_{\infty} = X_{\infty} n \rightarrow \infty |x[n]|^2$ , and  $P_{\infty} = \lim T \rightarrow \infty \int_0^T |x(t)|^2 dx$  and  $P_{\infty} = \lim N \rightarrow \infty \sum_{n=0}^{2N-1} |x[n]|^2$ . Using these we can compute each part of the given problem. Part (a): For this signal we find  $E_{\infty} = Z_{\infty} \int_0^{\infty} e^{-4t} dt = e^{-4t} \Big|_0^{\infty} = 1/4$ , and  $P_{\infty} = \lim T \rightarrow \infty \int_0^T e^{-4t} dt = \lim T \rightarrow \infty$

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Alan Victor Oppenheim is a Professor of Engineering at MIT's Department of Electrical Engineering and Computer Science. He is also a principal investigator in MIT's Research Laboratory of Electronics, at the Digital Signal Processing Group. His research interests are in the general area of signal processing and its applications. He is coauthor of the widely used textbooks Discrete-Time Signal Processing and Signals and Systems. He is also editor of several advanced books on signal processing. AI